

Aldebaran documentation

Quick search

Enter search terms or a module, class or function name.

Table Of Contents

- Site map
- What's new
- NAO Documentation
 - NAO - User Guide
 - NAO - Technical Guide
 - NAO - Technical overview
 - NAO - Actuator & Sensor list
 - NAO - Versions and Body Type
 - NAO H25**
 - H25 - Construction
 - H25 - LEDs
 - H25 - Joint position sensors
 - H25 - Contact and tactile sensors
 - H25 - Links
 - H25 - Joints
 - H25 - Masses
 - H25 - Motors
 - NAO H21
 - NAO T14
 - NAO T2
- ASK NAO Interface - V2 - User Guide
- Romeo Documentation
- NAOqi Developer guide
- Glossary
- Legal notices

On this page

- NAO H25
 - NAO H25

NAO H25

Technical specifications	
Construction <ul style="list-style-type: none"> H25 - Construction 	CPU <ul style="list-style-type: none"> Motherboard
Energy <ul style="list-style-type: none"> NAO - Battery 	Connectivity <ul style="list-style-type: none"> Connectivity
Interaction <ul style="list-style-type: none"> Loudspeakers Microphones NAO - Video camera Infra-Red 	Sensors <ul style="list-style-type: none"> FSRs Inertial unit Sonars

Optional devices

- [Available languages](#)
- [Laser head v.3.2](#)

Kinematics data	
<ul style="list-style-type: none"> H25 - Links H25 - Joints H25 - Masses H25 - Motors 	<ul style="list-style-type: none"> Effector & Chain definitions Predefined postures

NAO H25

